

# Democratizing Spatial Planning for Nature and People



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# Acknowledgements

- Jeff Hanson



- Joe Bennett



- Matt Strimas-Mackey



- Peter Arcese



- Nina Morrell



- Hugh Possingham



- Matt Watts



# The Why?

- Conservation planning = challenging
- Range of objectives and constraints
- Analytical tools tailored to specific tasks

## Proposal:

Flexible, powerful framework

+

User friendly (browser) interface



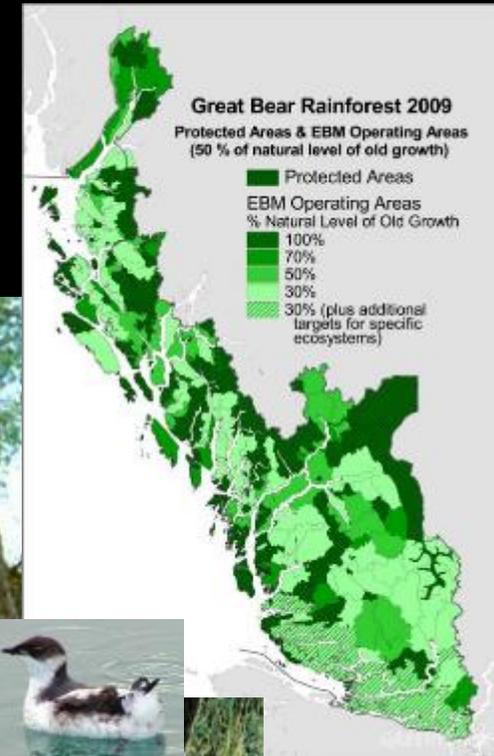
# Traditional Goal of Conservation Area Design

Prioritize and Conserve 'Intact' or 'Relic Ecosystems'

- Multiple criteria
- Decision support tools

Impractical in Human-dominated Landscapes

- No Benchmark Ecosystems
- Biological Survey Data Often Biased
- Many Threats Hard to Map

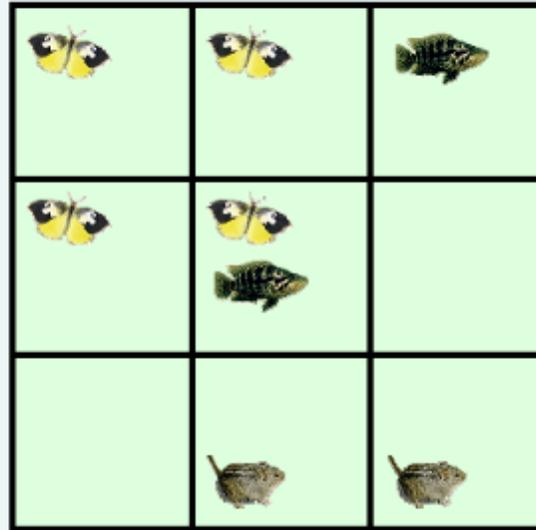


# Dry Forest / Savanna Habitats of the Georgia Basin

49% Converted to Human Use  
< 3% Pre-settlement Forest Intact  
> 80% Privately-owned  
>153 Species At Risk

- Most Imperiled Ecosystem in BC And Throughout the Pacific Northwest





Each planning unit costs 1

Boundary length modifier value = 1.5.

The species penalty factor for all three species is 10.

Illustrations by Bob Smith (DICE)

**What problem do we want to solve?**

**Score of the configuration being tested =**

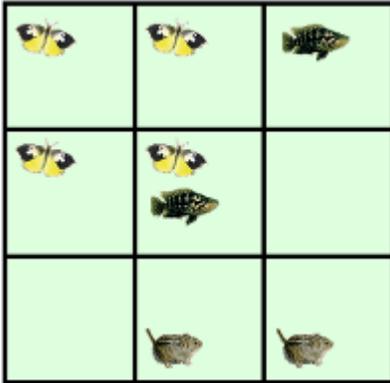
*Cost*

+

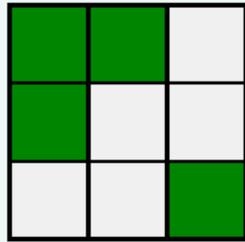
*Boundary Length Modifier* ×  
*Boundary Cost of the reserve system*

+

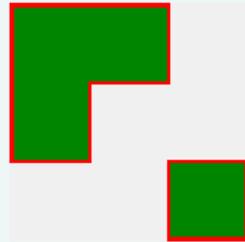
*Species Penalty Factor* ×  
*Penalty incurred for unmet targets*



## Measuring overall score



Total PU  
cost = 4



Boundary =  
 $12 * 1.5$



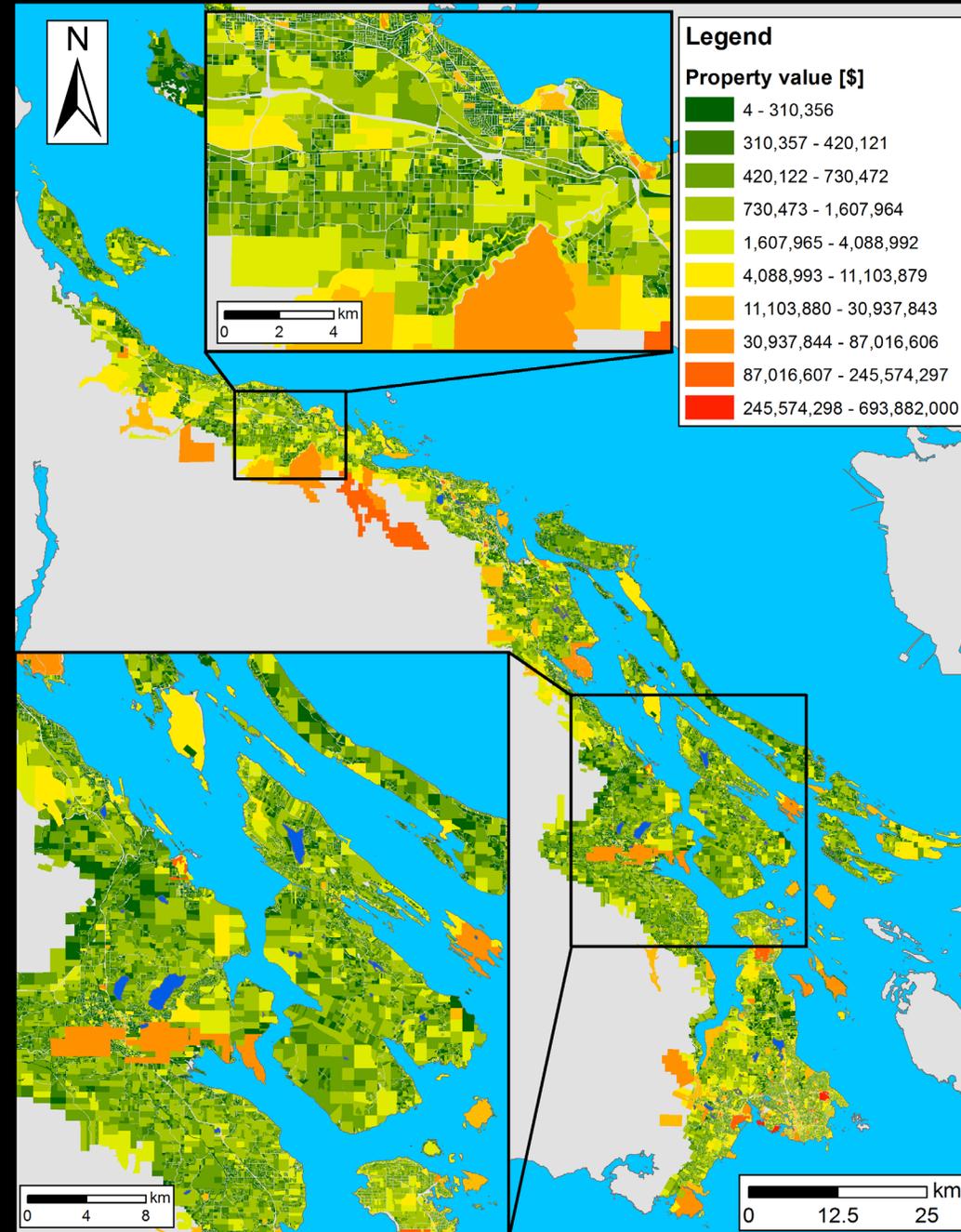
SPF = 10

Total  
score

32

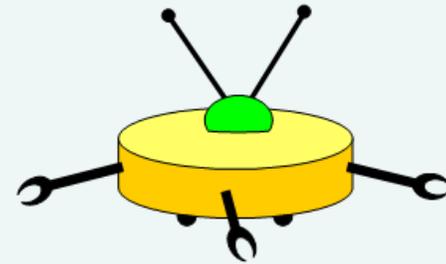
# Planning units

- Land base of the planning area: ~198,000 properties
- Possible solutions for a reserve system:  
 $2^{198,000} >$  atoms in the Universe
- How to optimize prioritization?



# Searching for life on Mars: a simulated annealing analogy

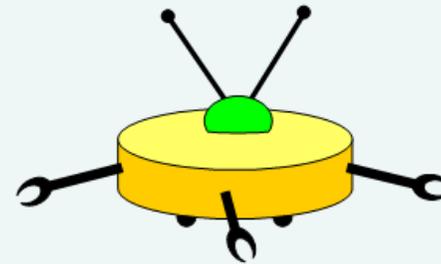
- Life will most likely to be found in low-lying areas
- Problem of finding the lowest-lying area on Mars using a robot is similar to finding the most efficient set of conservation areas (a lot of alternatives)
- How can simulated annealing help solve this problem?



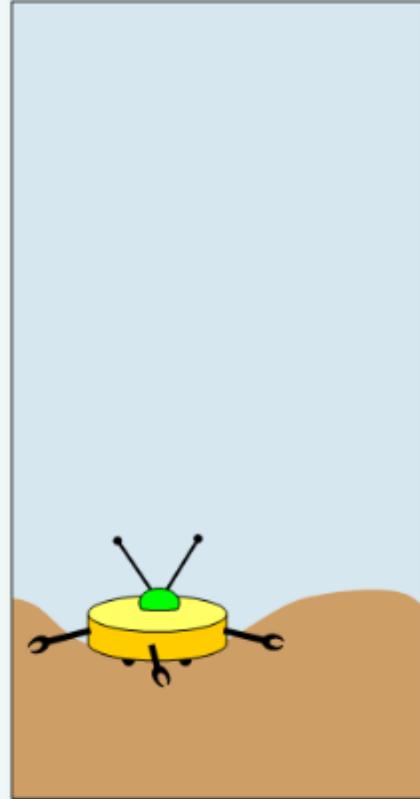
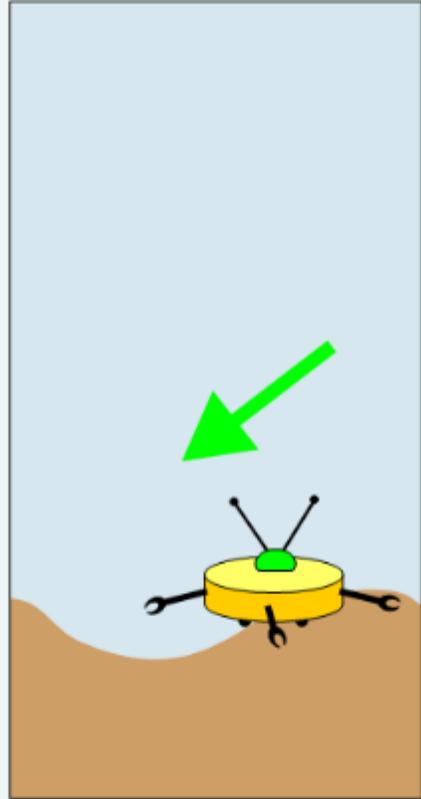
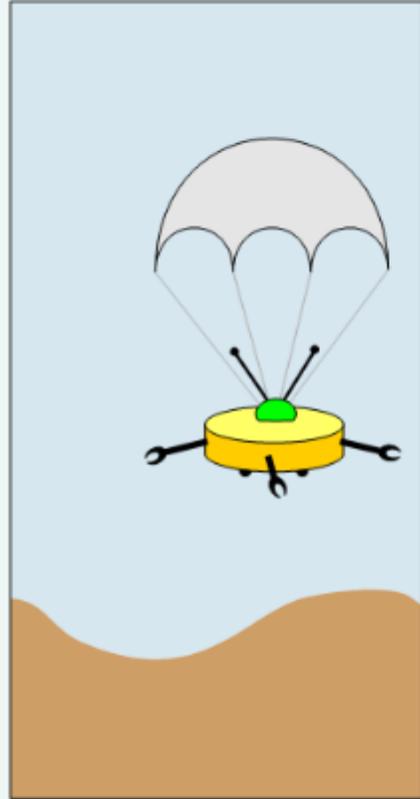
Source: Bob Smith (DICE)

# Simulated Annealing

- 1) Measure the elevation of the ground directly beneath the robot body.
- 2) Randomly choose an arm and measure the elevation of the ground beneath the arm.
- 3) If the ground beneath the arm is lower than the robot base then move to the point measured by the arm.

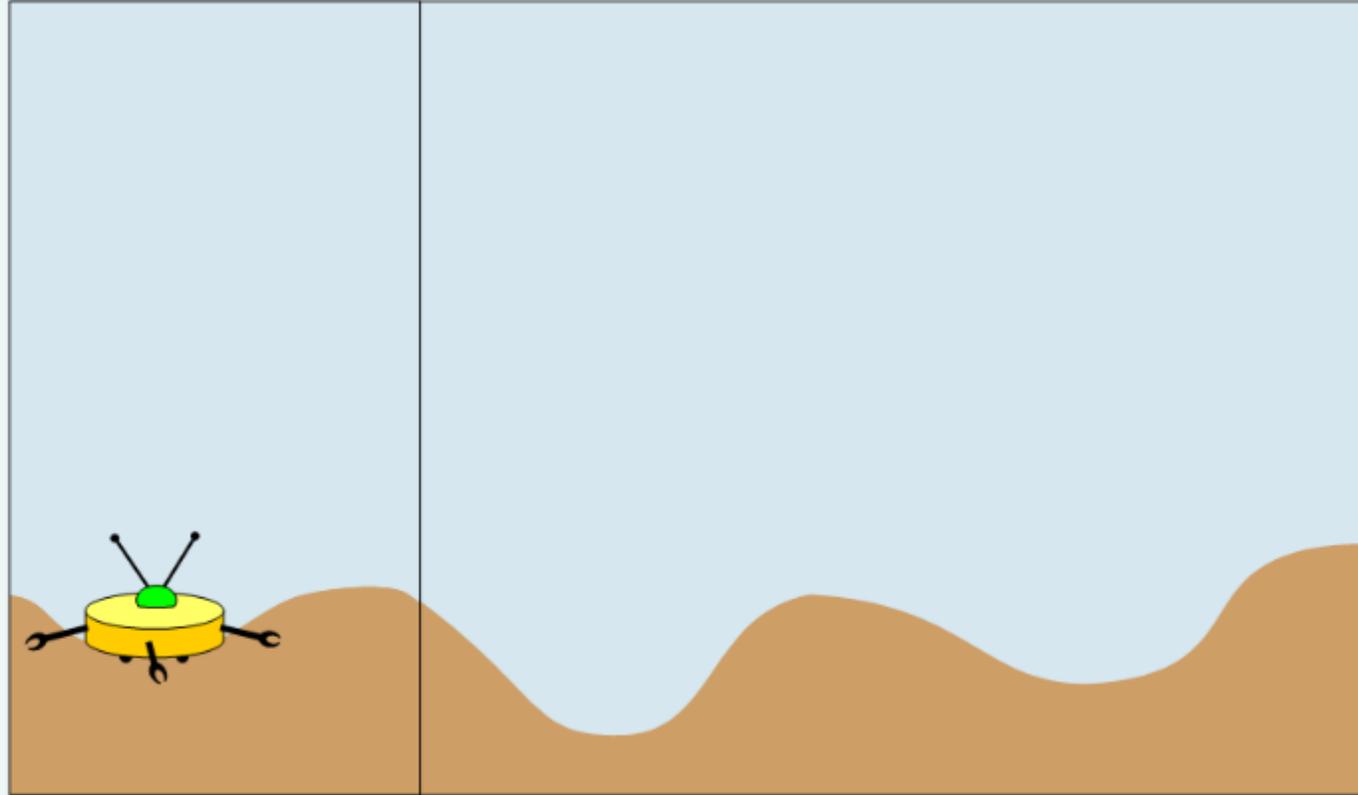


Source: Bob Smith (DICE)



Source: Bob Smith (DICE)

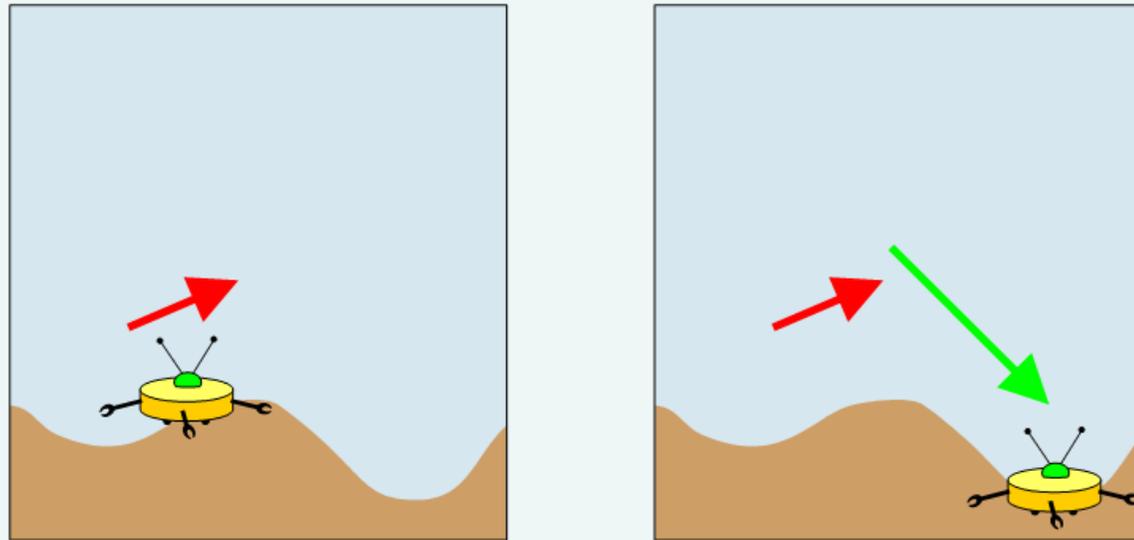
But...this is a flawed strategy as there are lower areas



Source: Bob Smith (DICE)

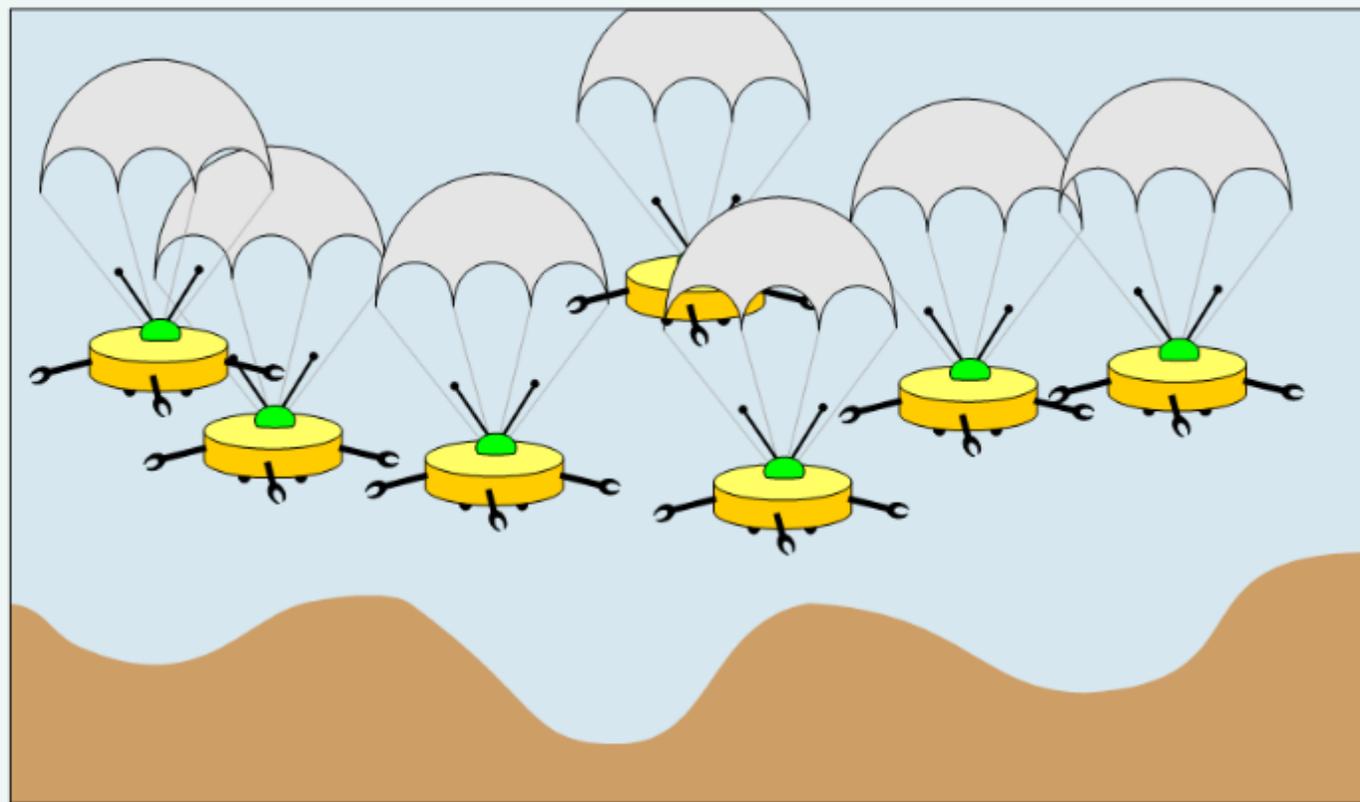
## Random backward steps

- Moves up a slope to try to move into neighbouring, lower-lying valleys
- Backward steps are more common at the beginning of the simulated annealing process



Source: Bob Smith (DICE)

# Repetition



Many robots (runs) results in many good solutions.

Source: Bob Smith (DICE)

# Where do we start?

- Conservation planning = challenging
- Range of objectives and constraints
- Analytical tools tailored to specific tasks

Flexible, powerful framework



+

User friendly (browser) interface

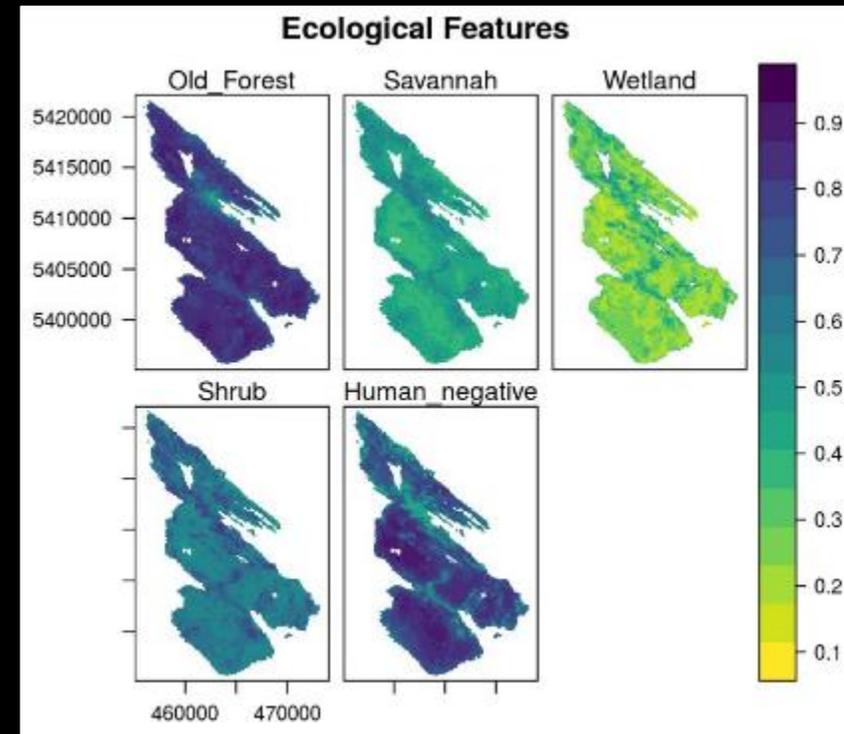




prioritizr.net



Hanson JO, Schuster R, Morrell N, Strimas-Mackey M, Watts ME, Arcese P, Bennett J, Possingham HP (2019). prioritizr: Systematic Conservation Prioritization in R. R package version 4.1.4.



# Why ?

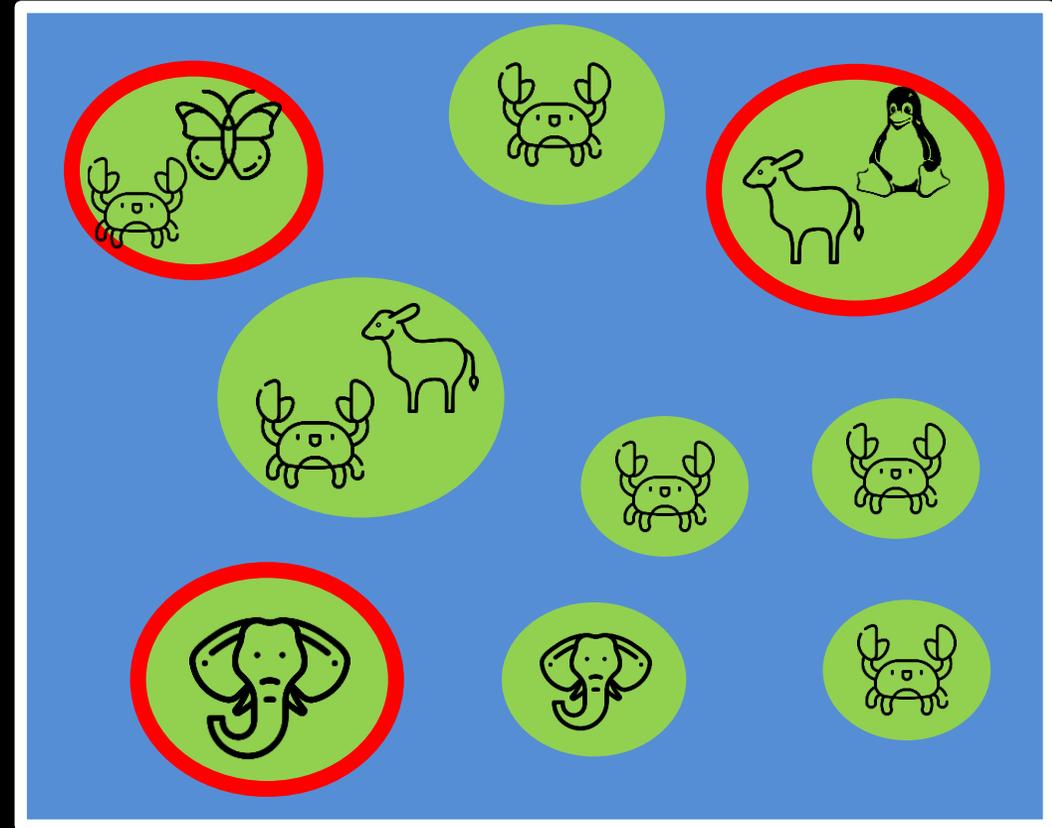
- It's free
- Diverse package ecosystem
- Reproducibility
- So many resources: Stackoverflow, tutorials, blogs, twitter, slack channels, mailing lists
- Flexible interface

# Decision science

- Goal: what is our vision for the future?
- Objective: what quantity are we maximizing/minimizing to help achieve the goal?
- Constraints: what things must our solution do to help achieve the goal?
- Decisions: what actions could we do to maximize/minimize the objective?

# Case-study: Reserve design

- Goal: conserve biodiversity
- Objective: min. # of islands
- Constraints: sufficient habitat for each species
- Decisions: which places should be protected?



# Design your problem

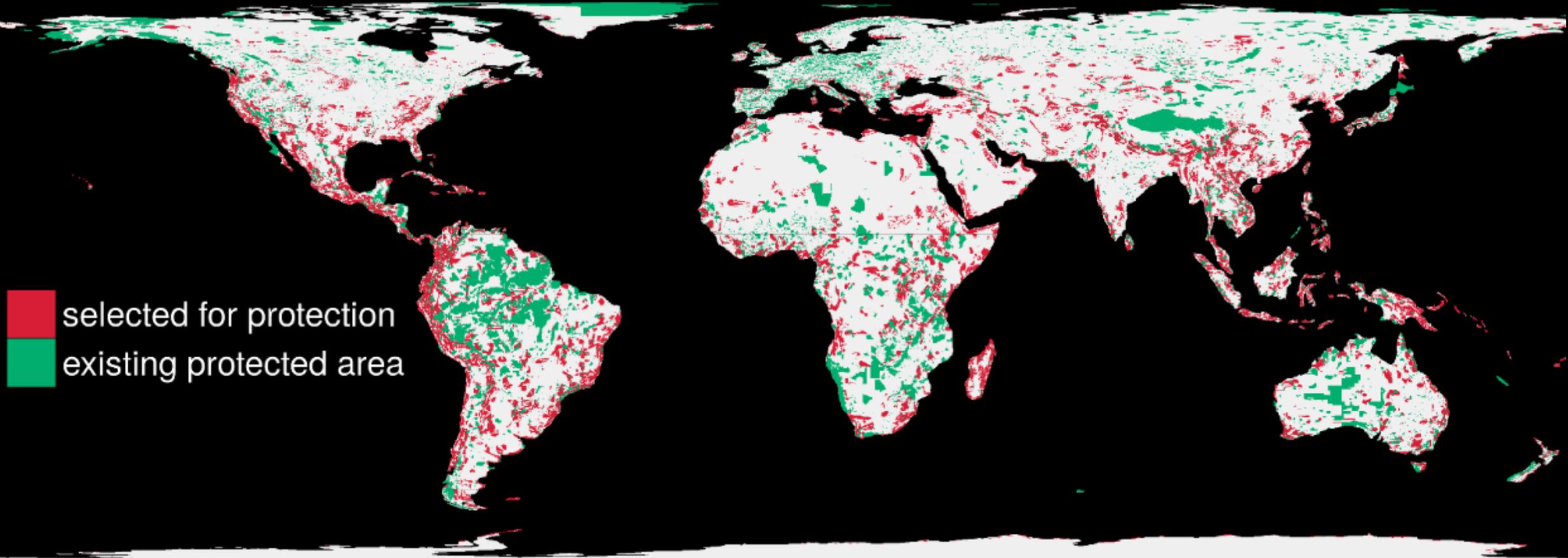
## Mental model

```
problem <- data +  
  objective +  
  constraints +  
  penalties  
  
solution <- solve(problem)
```

## Code

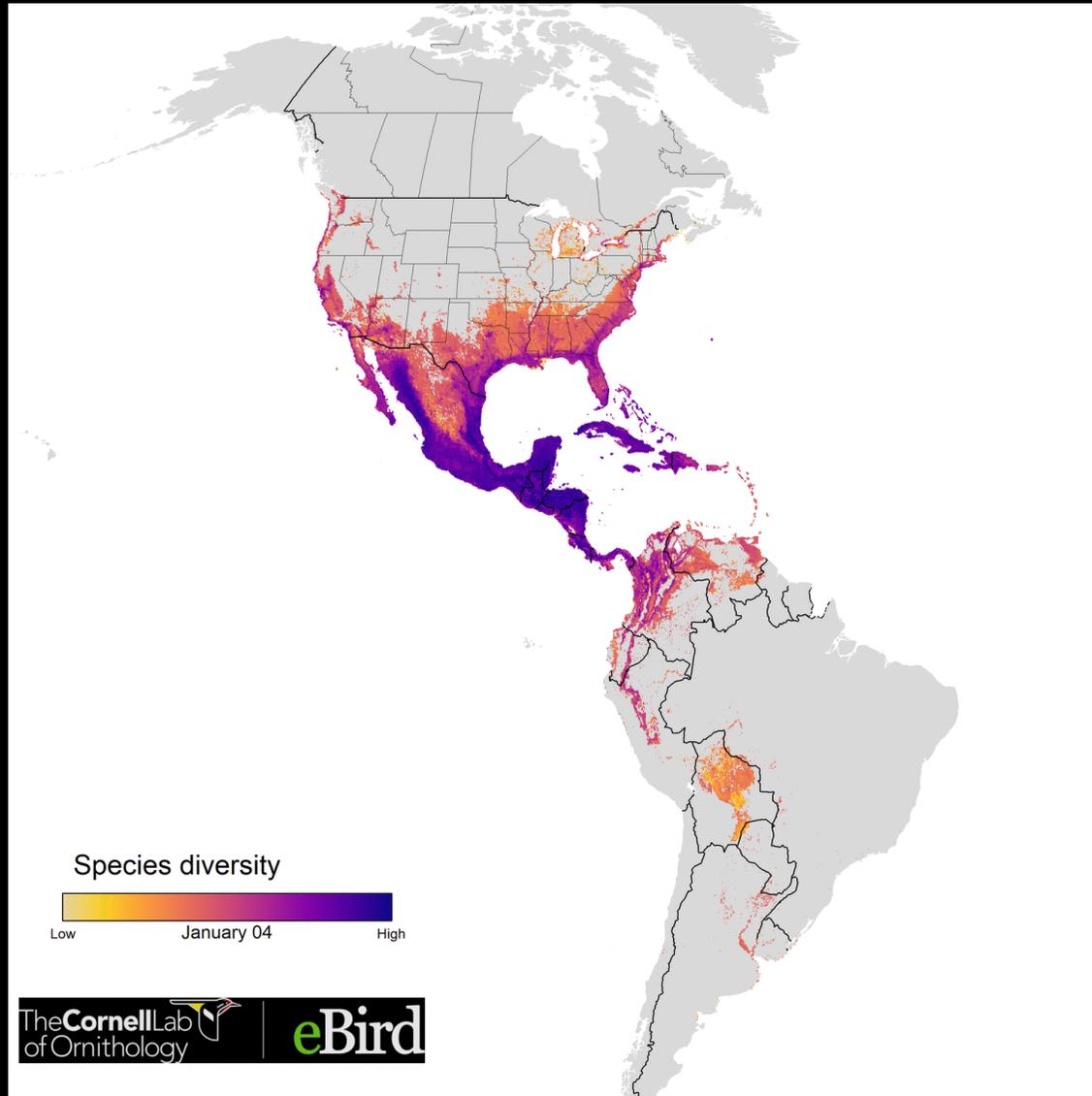
```
p <- problem(cost, features) %>%  
  add_min_set_objective() %>%  
  add_relative_targets(0.1) %>%  
  add_boundary_penalties(5)  
  
solution <- solve(p)
```

# Solve it fast!



1.5 million planning units + 22,644 species: 76 minutes

# Optimizing the conservation of migratory species over their full annual cycle



117 species

73 million km<sup>2</sup>

1.7 million unique locations

14 million checklists

≤ 30,420 features

1.05 million planning units

Analysis powered by:



Schuster et al. (2019) Nature Communications

# Facilitate Consensus Decisions on Protection



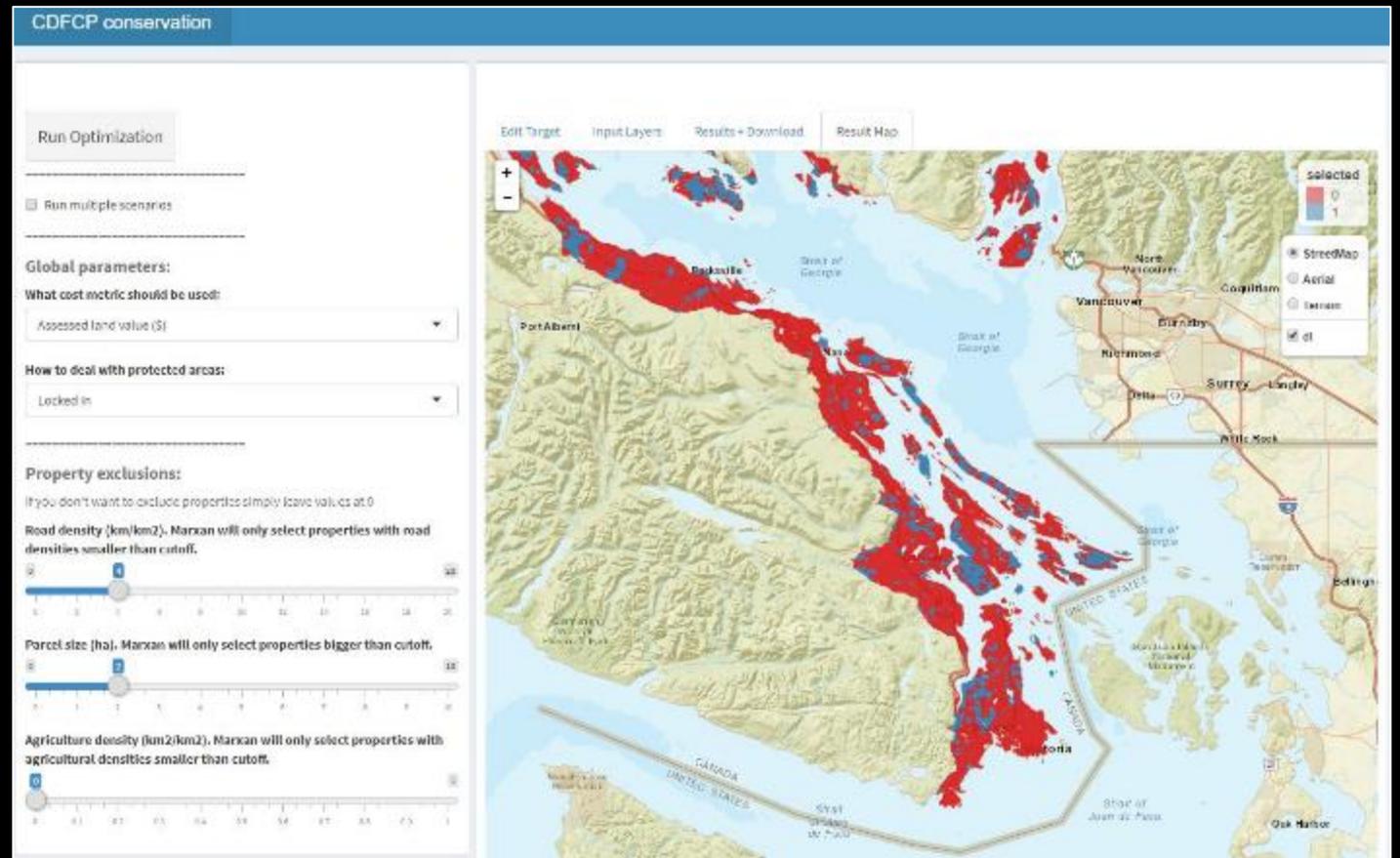
# Making prioritizr user friendly:



## A Prioritization Tool for the Conservation of Coastal Douglas-fir Forest and Savannah Habitats of the Georgia Basin

TUTORIAL AUTHORS: MORRELL, N., SCHUSTER, R., CROMBIE, M., & ARCESE P.  
<http://arcese.forestry.ubc.ca/marxan-tool/>

THE NATURE TRUST OF BRITISH COLUMBIA  
COASTAL DOUGLAS FIR CONSERVATION PARTNERSHIP  
DEPARTMENT OF FOREST AND CONSERVATION SCIENCES, UNIVERSITY OF BRITISH COLUMBIA

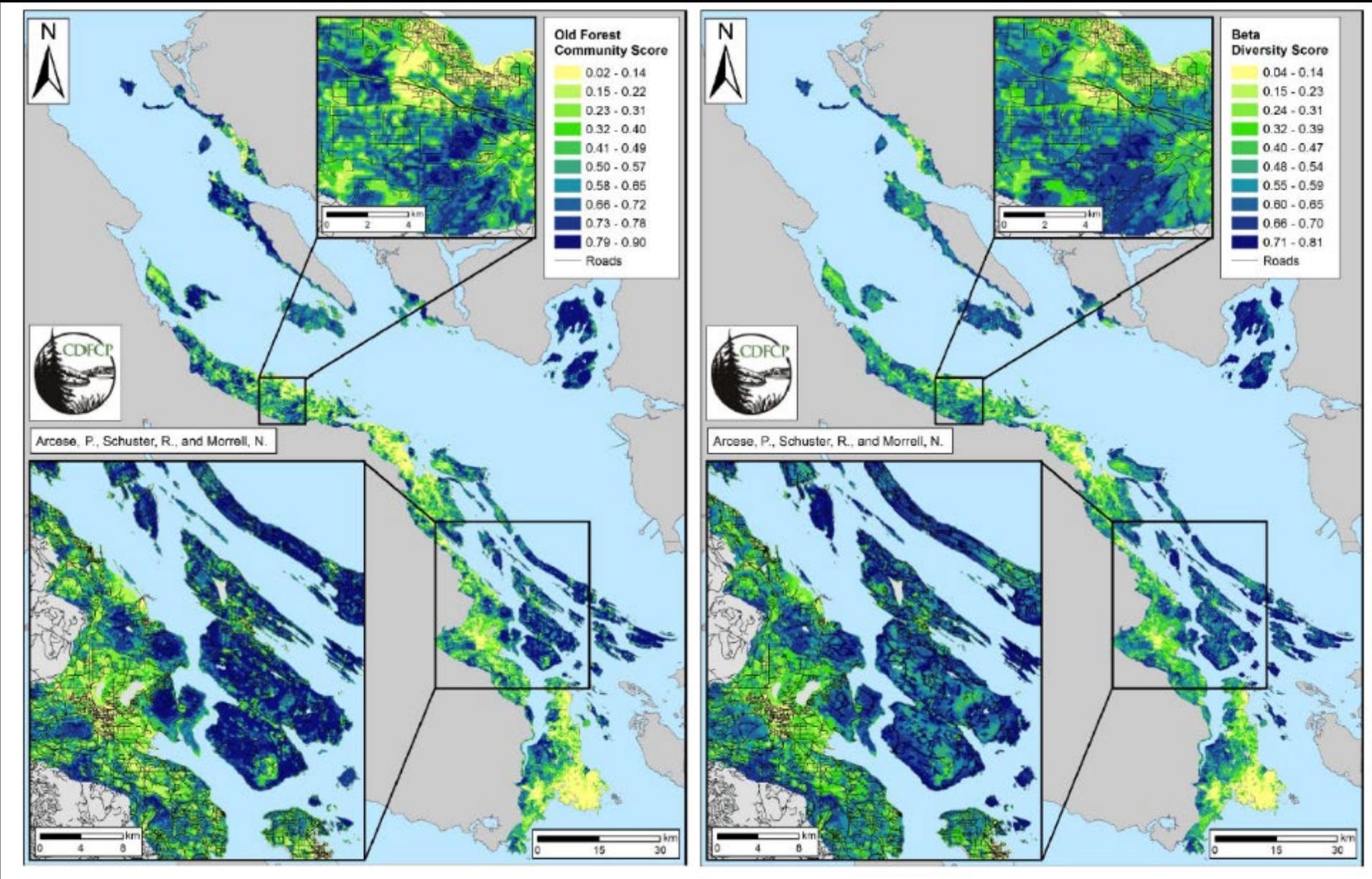


Old Forest Birds
Savannah Birds
Beta Diversity
Wetland Birds
Shrub Birds
Human Commensal Birds
Inverse of Hum Com Birds
Standing Carbon
Carbon Sequestration Potential
TEM Element Occurrence
SEI Coastal Bluff
SEI Herbaceous
SEI Older Forest
SEI Riparian
SEI Second Growth Forest
SEI Sparsely Vegetated
SEI Woodland
SEI Wetland

Native Plant Species Richness
Fish
Herptiles
California Buttercup
Contorted-pod Evening Primrose
Dense Flowered Lupine
Dense Spike-primrose
Foothill Sedge
Oregan Forestsnail
Maoun's Meadowfoam'
White Meconella
Coast Microseris
Marbeld Murrulet
Fragrant Popcorn
Sand-verbena Moth
Area

# Old forest community

# Beta diversity



# CDFCP tool tutorial (p.15+)

<http://arcese.forestry.ubc.ca/marxan-tool-cdfcp/>

*Table 1. Descriptions of the biodiversity feature layers included in the CDFCP tool. Target values for each of these layers can be specified in the table found under the 'Edit Target' tab in the CDFCP tool interface.*

<b>Old Forest Birds (OF)</b>	A composite distribution map based on probability of occurrence of birds associated with old forest habitat (Schuster and Arcese 2014). See Appendix A.
<b>Savannah Birds (SAV)</b>	A composite distribution map based on probability of occurrence of birds associated with savannah habitat (Schuster and Arcese 2014). See Appendix A.
<b>Shrub Birds (SHR)</b>	A composite distribution map based on the probability of occurrence of birds associated with shrub habitat. See Appendix A.
<b>Wetland Birds (WET)</b>	A composite distribution map based on probability of occurrence of birds associated with wetland and riparian habitats (Schuster and Arcese, unpublished). See Appendix A.
<b>Human Commensal Birds (HUM)</b>	A composite distribution map based on probability of occurrence of birds associated with urban and rural human landscapes (Schuster and Arcese, unpublished). When targets are set for this feature, the tool will seek planning units least likely to host commensal species. See Appendix A.



COASTAL DOUGLAS-FIR  
& ASSOCIATED ECOSYSTEMS  
CONSERVATION PARTNERSHIP

CONSERVATION  
STRATEGY  
2015

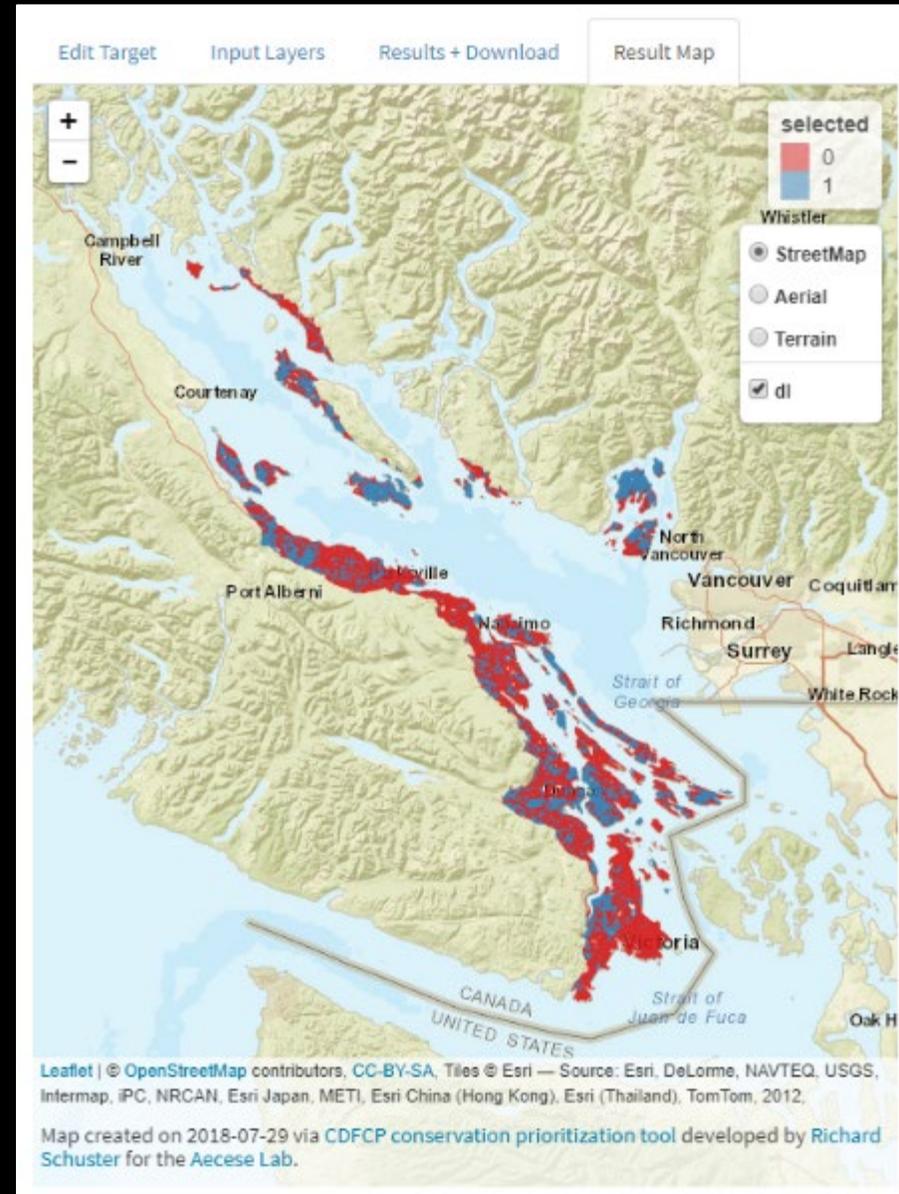
# Applications?



Acquire Biodiverse Parcels

Minimize Management Costs,  
Maximize Return on  
Conservation Investments

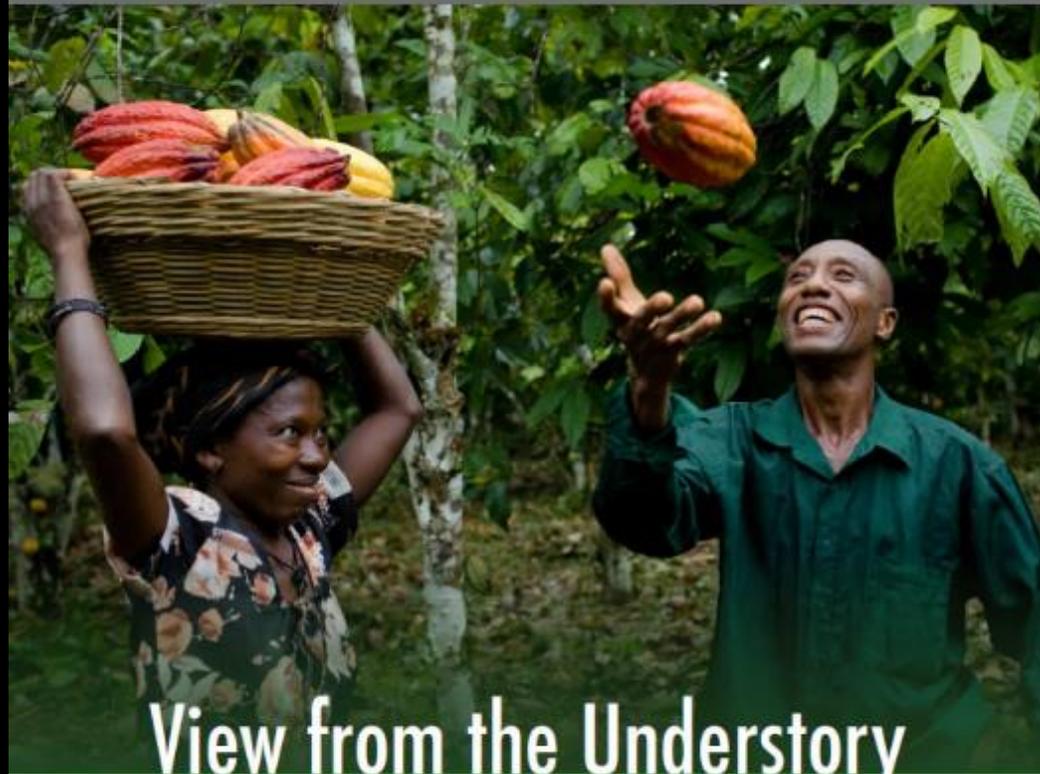
Develop Contact Lists to Engage  
Private Landowners in  
Conservation at Landscape  
Scales



# Payments for Ecosystem Services

\$6 Billion Invested  
to 2016 in Carbon

Ecosystem Marketplace  
A FOREST TRENDS INITIATIVE



## View from the Understory

State of Forest Carbon Finance 2016

Premium Sponsors:



**althelia**  
ecosphere



**ecosphere+**



**NewForests**

Supporters:

MacArthur  
Foundation



Sponsors:

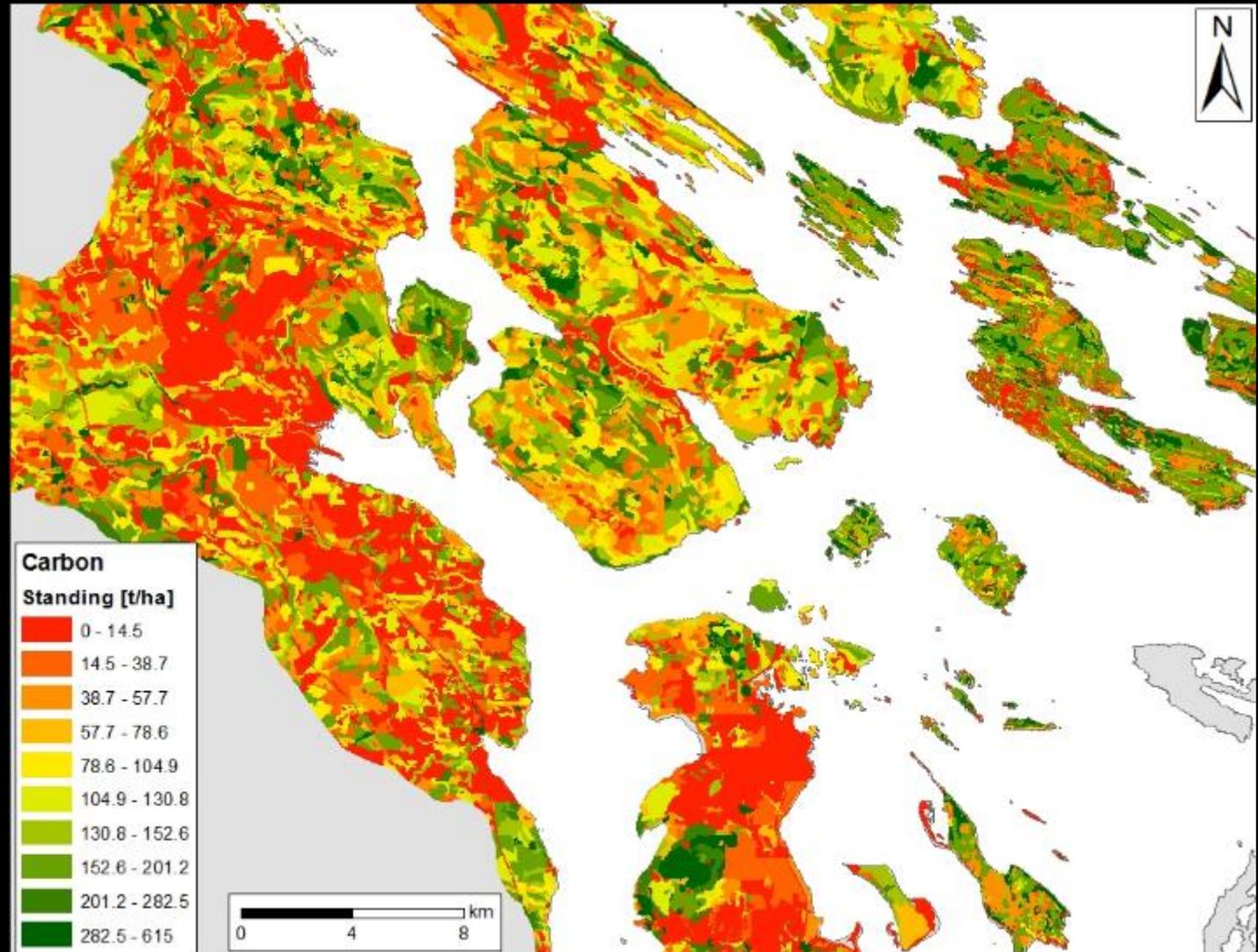


**BAKER & MCKENZIE**

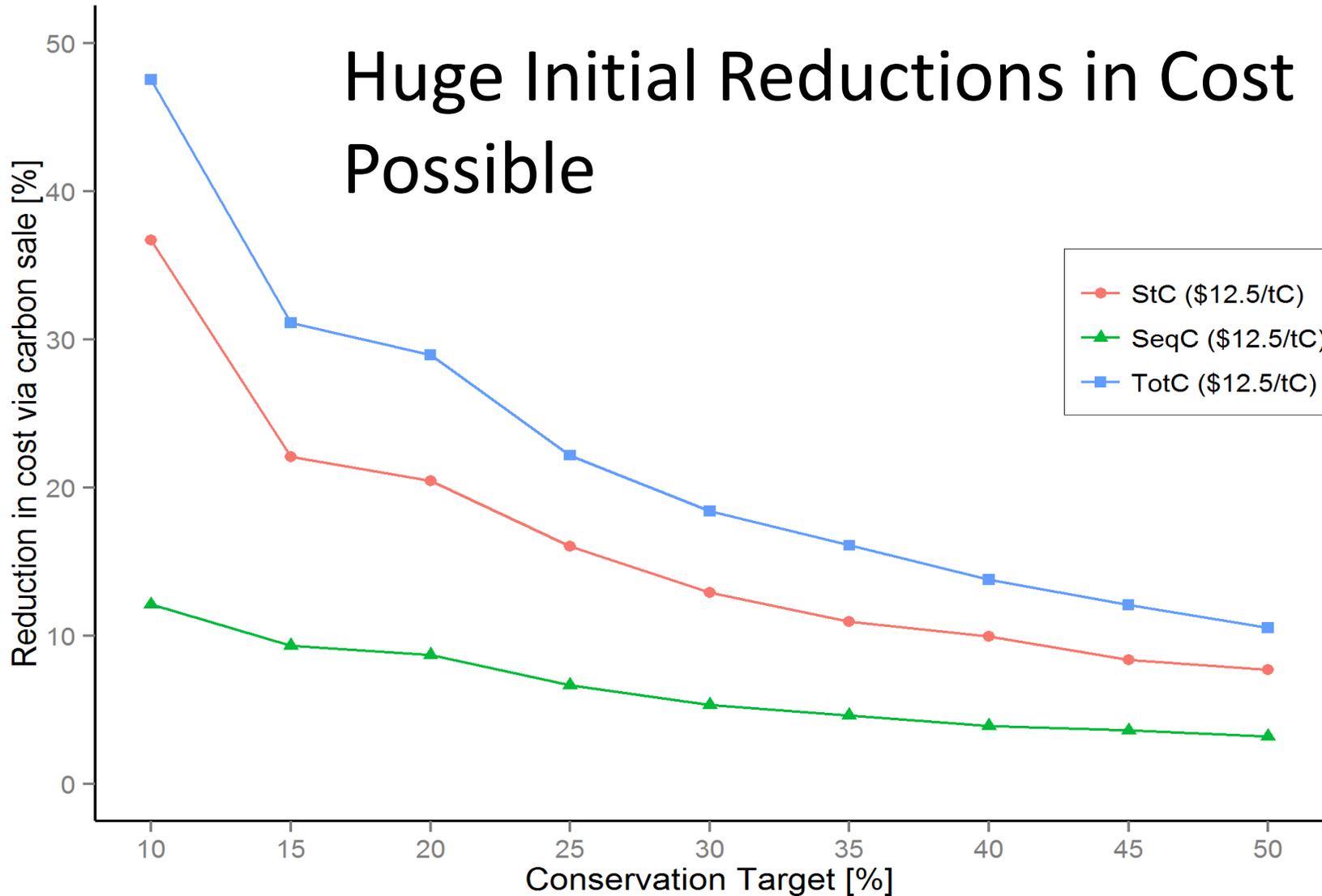
# Synergies: High Value Forests Have Standing Carbon In Excess of 200 t/ha

Standing Carbon in High Value Forests in the Georgia Basin is Currently Worth \$4-10K/ha

~3-15% of Acquisition Cost



# Biodiversity - Carbon



# Strategic Investment for 'Co-benefits'

Standing /  
Sequestered  
Carbon



Water Quality  
/ Supply



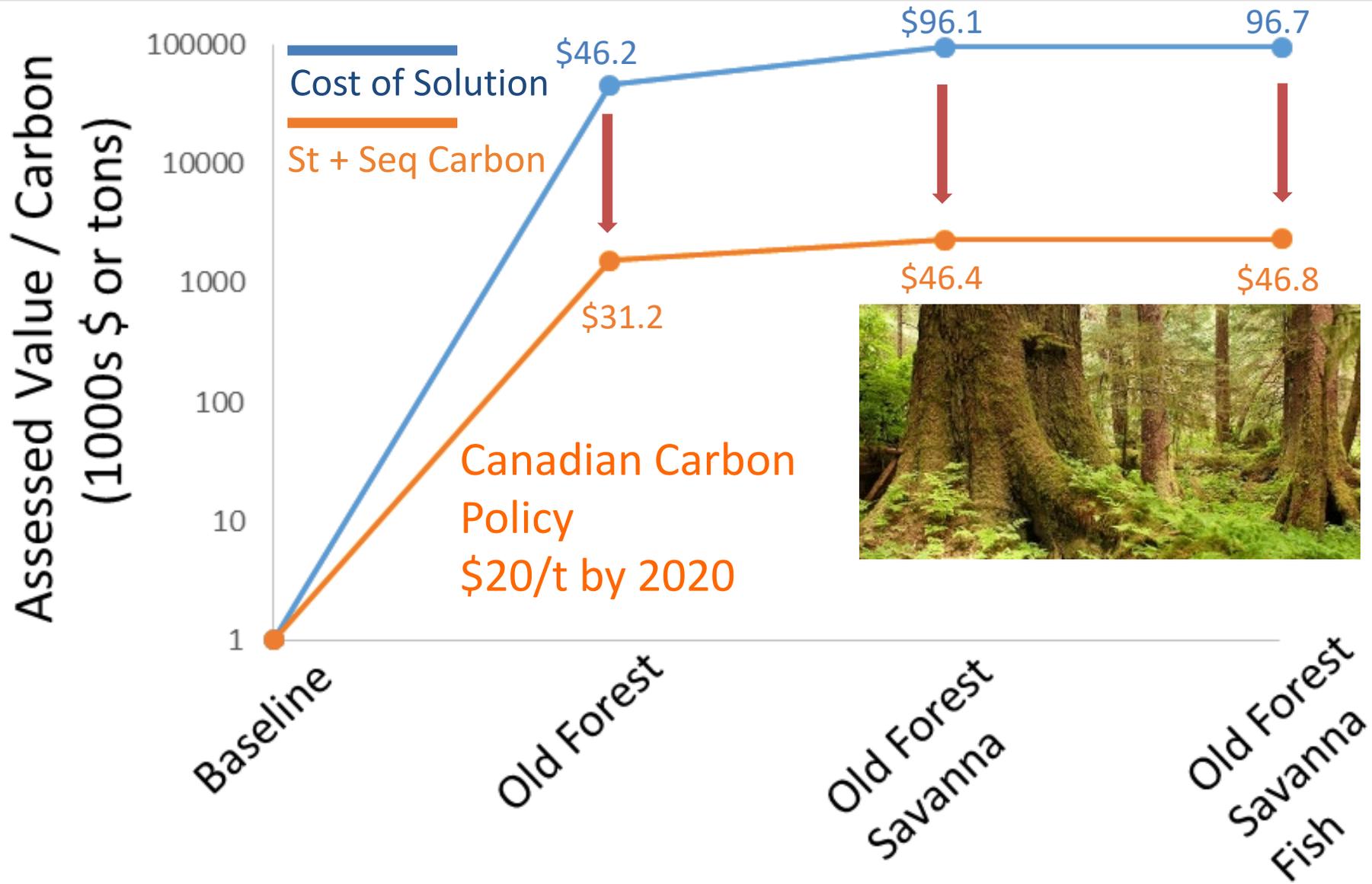
Beneficial Farm  
Practices



# Coastal Douglas-fir Carbon Co-Benefit

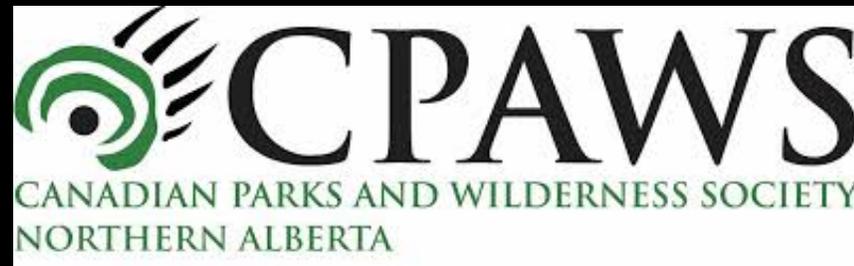


# Coastal Douglas-fir Carbon Co-Benefit



# Climate Adaptive Planning for British Columbia

- Recently started 3 year project
- Leads: Oscar Venter and Peter Arcese
- Partners:



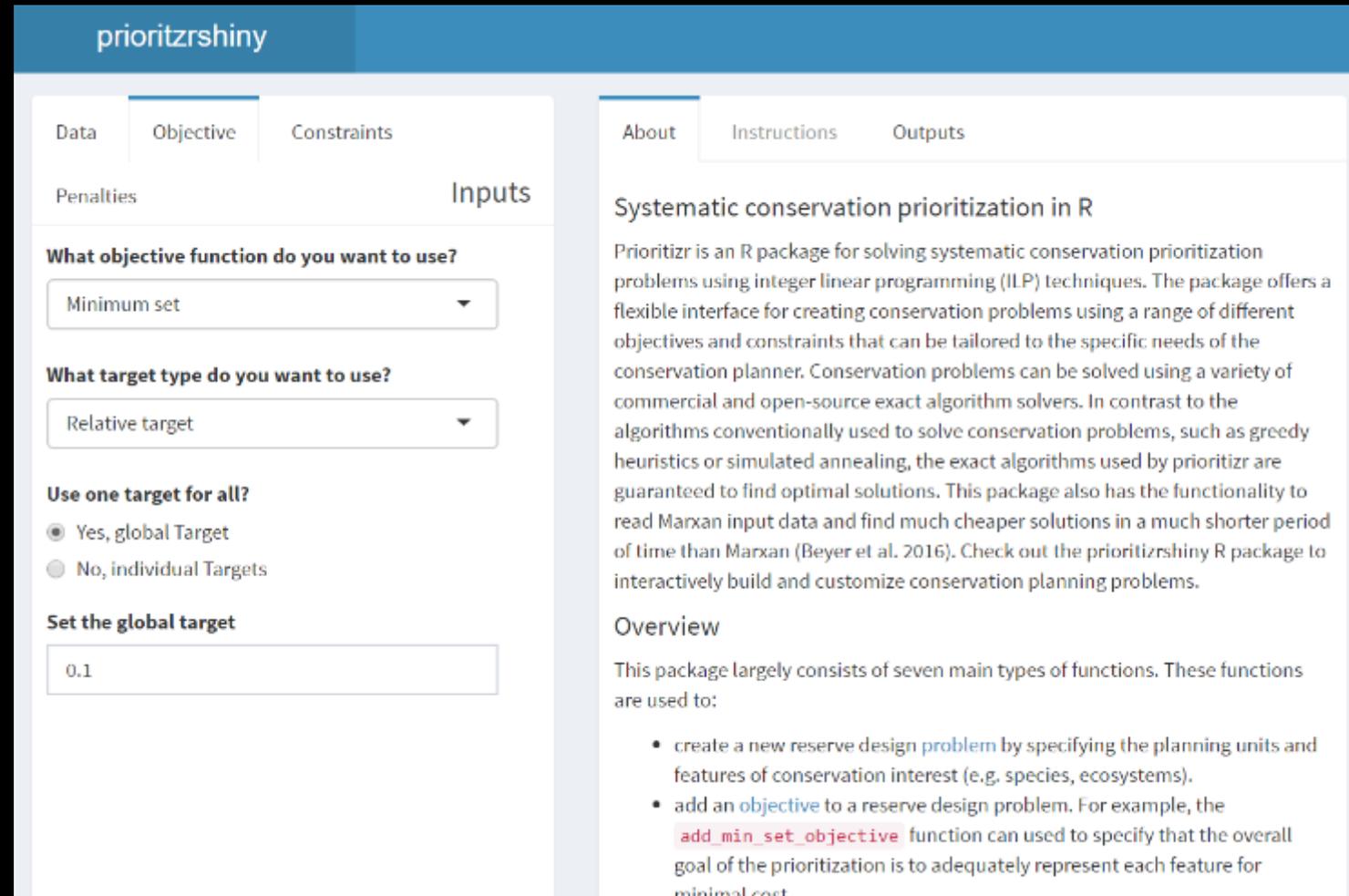
**What's next?**

# priorizrshiny (in development)

## Code

```
p <- problem(areas, feats) %>%  
  add_min_set_objective() %>%  
  add_relative_targets(0.1) %>%  
  add_boundary_penalties(5) %>%  
  add_binary_decisions() %>%  
  add_rsymphony_solver()  
  
solution <- solve(p)
```

## User interface



The screenshot shows the web interface for the 'priorizrshiny' application. The interface is divided into two main sections: 'Data' and 'Objective'. The 'Objective' section is currently active and contains several configuration options:

- Penalties**: A section for setting penalties, currently showing '5'.
- Inputs**: A section for setting inputs, currently showing '0.1'.
- What objective function do you want to use?**: A dropdown menu with 'Minimum set' selected.
- What target type do you want to use?**: A dropdown menu with 'Relative target' selected.
- Use one target for all?**: Radio buttons for 'Yes, global Target' (selected) and 'No, individual Targets'.
- Set the global target**: A text input field containing '0.1'.

The right-hand side of the interface contains a sidebar with navigation tabs: 'About', 'Instructions', and 'Outputs'. The 'About' tab is selected, displaying the following text:

### Systematic conservation prioritization in R

Priorizr is an R package for solving systematic conservation prioritization problems using integer linear programming (ILP) techniques. The package offers a flexible interface for creating conservation problems using a range of different objectives and constraints that can be tailored to the specific needs of the conservation planner. Conservation problems can be solved using a variety of commercial and open-source exact algorithm solvers. In contrast to the algorithms conventionally used to solve conservation problems, such as greedy heuristics or simulated annealing, the exact algorithms used by prioritizr are guaranteed to find optimal solutions. This package also has the functionality to read Marxan input data and find much cheaper solutions in a much shorter period of time than Marxan (Beyer et al. 2016). Check out the prioritizrshiny R package to interactively build and customize conservation planning problems.

### Overview

This package largely consists of seven main types of functions. These functions are used to:

- create a new reserve design **problem** by specifying the planning units and features of conservation interest (e.g. species, ecosystems).
- add an **objective** to a reserve design problem. For example, the `add_min_set_objective` function can be used to specify that the overall goal of the prioritization is to adequately represent each feature for minimal cost.



# NCC – Carleton partnership



- **Tools for prioritization of conservation investments**
- Phase 1: Modernize NCC's conservation prioritization methods
  - Systematic Reserve Acquisition Prioritization tools
  - Tools aimed at optimizing stewardship decisions
- Phase 2: democratize conservation decisions beyond NCC



# Take home message

Flexible + powerful framework  
+  
User friendly browser interface  
=  
A novice stakeholder can  
devise a high-quality,  
data-driven spatial plan in just  
one hour.

